

Sensors for Small Forces

-0,5 ... 0,5 N to -500 ... 500 N

These slim sensors are designed for dynamic and quasistatic tensile and compression forces. Depending on the design of the sensor, it is possible to measure small forces in measuring ranges between $-0.5 \dots 0.5$ N to $-500 \dots 500$ N. As a result of the high sensitivity of the integrated measuring element and special constructive measures during force application, the sensors' threshold is less than one millinewton. The sensors have a sealed housing and are designed for use in industry and the laboratory. Installation of the sensors directly into the structure is made possible by the thread on the shaft. Force is applied to the front side.

- 3 calibrated measuring ranges
- Highly sensitive, for forces from 1 mN
- For tensile and compression forces
- Slim design for small sensor distances

Description

The sensors are based on the piezoelectric measurement principle. The force acting on the highly sensitive transversal measuring element generates a proportional charge at the signal output. The measuring amplifier to be placed downstream (e.g., ICAM Type 5073A...) or process monitoring system (e.g., maXYmos Type 5867B... /5877A...) converts this into a process signal or curve that can be evaluated (e.g., 0 ... 10 V). The slim, pen-like structural shape of the sensor bodies and the force application on the axial tapped hole are important features of these sensors.

Application

Due to their slim geometry, the sensors are especially suitable for confined spaces, e.g., to simultaneously measure objects that are placed close together.

Due to the special property of the piezoelectric measuring element – almost constant measurement accuracy over a wide force range – the same sensor can be used across a large force spectrum. This advantage is further supported by the possibility of switching between measuring ranges by using appropriate amplifiers (ICAM Type 5073A...). This makes it possible to measure highly diverse parts at the same measuring station. The 'wide range measuring chain' also offers decisive advantages for use in a laboratory, where frequent sensor changes are part of everyday work. In addition, the extremely high overload protection when using the lower measuring ranges means there is no need for costly protective measures.

Type 9203, 9205, 9207, 9215A, 9217A



Type 9203 Type 9205 Type 9207 Type 9215A Type 9217A

Application Examples

- Contact measurement on keys, switches, relays, etc.
- Measuring spring characteristics
- Measuring pull-out forces on plug contacts
- Construction of highly sensitive miniature measuring platforms
- Force measurement on installation machines, robots, micromanipulators, etc.

Caution

These force sensors are very sensitive measuring instruments. The highest amount of vigilance is required when working with these sensors, as they are not equipped with a mechanical fuse against overload.



Technical Data

Please note that all technical data and further information in this data sheet is subject to change at any time without prior notice.

Overload F ₂ N -600 / 600 -75 / 150 -30 / 300 -600 / 600 Calibrated measuring ranges, F ₂ N 0 500 -50 50 0 200 0 500 10 % N 0 50 -5 5 -5 5 0 200 0 500 1 % N 0 50 -5 5 -5 5 0 20 0 50 1 % N 0 50 -5 5 -5 5 0 20 0 50 1 % N 0 50 -5 5 -5 5 0 20 0 50 1 % N 0 50 -5 5 -5 5 0 20 0 50 1 % N 0 50 -5 5 -5 5 0 50 0 50 1 % N 0 50 -5 5 -5 5 0 50 0 50 1 % N 0 50 -5 5 -5 5 0 50 0 50 1 % 1 % 0 50 0 50 0 50 0 50 </th <th></th> <th>Type</th> <th>9203</th> <th>9205</th> <th>9207</th> <th>9215A</th> <th>9217A</th>		Type	9203	9205	9207	9215A	9217A
Calibrated measuring ranges, F _z N 0500 -5050 -5050 0200 0500 0	Measuring range F _z	N	-500 500	-50 50	-50 50	-20 200	-500 500
Calibrated measuring ranges, F _z N 0500 -5050 -5050 0200 0500 0	Overload Fz	N	-600 / 600	-75 / 150	-75 / 150	-30 / 300	-600 / 600
10 % N 0 50 -5 5 -5 5 0 20 0500 10 % N 0 50 050 050 1 % N 0 50 -0.5 0.5 -0.5 0.5 0 20 0 50 1 % N 0 50 -0.5 0.5 -0.5 0.5 0 20 0 50 1 % N 0 50 -0.5 0.5 -0.5 0.5 0 20 0 50 2	Calibrated measuring ranges, Fz						
10 % N	100 %	N	0 500	<i>-</i> 50 50	-50 50	0 200	0 500
1 %							0 –500
1 % N 0 5	10 %	N	0 50	<i>-</i> 5 5	-5 5	0 20	0 50
Threshold, F₂			0 –50				0 –50
Sensitivity, F₂ pC / N ≈-40 ≈-115 ≈-115 ≈-95 ≈-105 Linearity, all measuring ranges %FSO ≤±1 ×102 ×102 ×102 ×102 ×102 ×102 ×102 ×102 ×102 ×102 ×103 ×103 ×10 <td>1 %</td> <td>N</td> <td>0 5</td> <td>-0.5 0.5</td> <td>-0.5 0.5</td> <td>0 2</td> <td>0 5</td>	1 %	N	0 5	-0.5 0.5	-0.5 0.5	0 2	0 5
Linearity, all measuring ranges %FSO ≤±1 Linearity, typically %FSO - - - - - <0.2	Threshold, F _z	N	<0,001	<0,0005	<0,0005	<0,0005	<0,001
Linearity, typically %FSO − − − − − − − − − − − − − − − − − − −	Sensitivity, F _z	pC / N	≈–40	≈–115	≈–115	≈–95	≈–105
Hysteresis, all measuring ranges %FSO	Linearity, all measuring ranges	%FSO		'	≤±1	'	-
Hysteresis, all measuring ranges %FSO	Linearity, typically	%FSO	_	_	_	_	<0.2
Hysteresis, typically %FSO − − − − − − − − − − − − − − − − − − −	Hysteresis, all measuring ranges	%FSO	≤±1	≤±0,5	≤±0,5	≤±1	≤±1
Side load sensitivity $F_{x,y} \rightarrow F_z$ N / N ≤±0,25 ≤±0,05 ≤±0,05 ≤±0,05 ≤±0,02 Sending moment, max., M _{x,y} $N \cdot m$ 0,59 0,25 0,25 0,5 1,78 Sensitivity to bending moment $M_{x,y} \rightarrow F_z$ $N / N \cdot m$ 0,59 0,25 0,25 0,5 1,78 Sensitivity to bending moment $M_{x,y} \rightarrow F_z$ $N / N \cdot m$ 0,67 0,15 0,15 1,0 1,35 Rigidity, c_z (F_z) $N / \mu m$ =40 ≈4 ≈4 ≈100 ≈15 Natural frequency, f_n (F_z) kHz >27 >10 >10 >10 >50 >20 Acceleration sensitivity axial N / g <0,02 <0,03 <0,03 <2 ⋅ 10 ⁻³ <0,035 <	Hysteresis, typically	%FSO	_	_	_	_	<0.2
Side load sensitivity $F_{x,y} \rightarrow F_z$ N / N ≤±0,25 ≤±0,05 ≤±0,05 ≤±0,05 ≤±0,02 Sending moment, max., M _{x,y} $N \cdot m$ 0,59 0,25 0,25 0,5 1,78 Sensitivity to bending moment $M_{x,y} \rightarrow F_z$ $N / N \cdot m$ 0,59 0,25 0,25 0,5 1,78 Sensitivity to bending moment $M_{x,y} \rightarrow F_z$ $N / N \cdot m$ 0,67 0,15 0,15 1,0 1,35 Rigidity, c_z (F_z) $N / \mu m$ =40 ≈4 ≈4 ≈100 ≈15 Natural frequency, f_n (F_z) kHz >27 >10 >10 >10 >50 >20 Acceleration sensitivity axial N / g <0,02 <0,03 <0,03 <2 ⋅ 10 ⁻³ <0,035 <	Side load ¹⁾ , max., F _{xv}	N	25	10	10	90	50
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$,						
Bending moment, max., Mxy N·m 0,59 0,25 0,25 0,5 1,78 Sensitivity to bending moment N/ N·m - ≤±3 ≤±3 ≤±20 - Mxy → Fz N / N·m 0,67 0,15 0,15 1,0 1,35 Rigidity, c₂ (F₂) N / μm ≈40 ≈4 ≈4 ≈100 ≈15 Natural frequency, fn (F₂) kHz >27 >10 >10 >50 >20 Acceleration sensitivity N/ g <0,02	-	N/N	≤±0,25	≤±0,05	≤±0,05	≤±0,05	≤±0,02
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		N⋅m	0,59	0,25	0,25	0,5	1,78
N·m 0,67 0,15 0,15 1,0 1,35	Sensitivity to bending moment						
Torque, max., M_z N·m 0,67 0,15 0,15 1,0 1,35 Rigidity, c_z (F_z) N / μm ≈40 ≈4 ≈4 ≈100 ≈15 Natural frequency, f_n (F_z) kHz >27 >10 >10 >50 >20 Acceleration sensitivity axial N / g <0,02	$M_{x,y} \rightarrow F_z$	N / N·m	_	≤±3	≤±3	≤±20	_
Natural frequency, fn (Fz) kHz >27 >10 >50 >20 Acceleration sensitivity axial N / g <0,02	Torque, max., M _z	N⋅m	0,67	0,15	0,15	1,0	1,35
Natural frequency, fn (Fz) kHz >27 >10 >50 >20 Acceleration sensitivity axial N / g <0,02	Rigidity, c _z (F _z)	N / μm	≈40	≈4	≈4	≈100	≈15
Acceleration sensitivity axial N / g		kHz	>27	>10	>10	>50	>20
radial N / g <0,002 <0,003 <0,003 <4 · 10 ⁻⁴ <0,0022 Operating temperature range °C -150 240 -50 150 -50 150 -50 180 -50 150 Temperature coefficient of sensitivity, F₂ % / °C ≈-0,01 ≈-0,02 ≈-0,02 ≈<0,04	Acceleration sensitivity						
Operating temperature range °C −150 240 −50 150 −50 180 −50 150 Temperature coefficient of sensitivity, F₂ % / °C ≈−0,01 ≈−0,02 ≈−0,02 ≈<0,04	axial	N/g	<0,02	<0,03	<0,03	<2 · 10 ⁻³	<0,035
Temperature coefficient of sensitivity, F_z % / °C ≈-0,01 ≈-0,02 ≈-0,02 ≈-0,04 ≈<0,04 ≈<0,04 lnsulation resistance at 20 °C Ω >10 ¹³ Ω ×22 ≈26 ≈26 ≈15 ≈45 Ω ×15 ×45 Ω ×16 ×15 ×45 Ω ×16 ×16 ×16 ×16 ×16 ×16 ×16 ×16 ×16 ×16	radial	N/g	<0,002	<0,003	<0,003	<4 · 10 ⁻⁴	<0,0022
of sensitivity, F_z % / °C ≈-0,01 ≈-0,02 ≈-0,02 ≈<0,04 ≈<0,04 Insulation resistance at 20 °C Ω >10³³ Capacity C pF ≈22 ≈26 ≈26 ≈15 ≈45 Connection KIAG KIAG KIAG M4x0.35 KIAG Protection class (with connected cable) EN 60529 IP65 Case material DIN 1,4542 Weight g 13 19 19 2.5 16 Tightening torque, max., MA N·m 0.2 0.2 0.5 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 0.5 0.2 0.2 0.5	Operating temperature range	°C	-150 240	-50 150	-50 150	-50 180	-50 150
Insulation resistance at 20 °C Ω PF ≈22 ≈26 ≈26 ≈15 ≈45 ×45	Temperature coefficient						
Capacity C pF ≈22 ≈26 ≈26 ≈15 ≈45 Connection KIAG KIAG KIAG M4x0.35 KIAG Protection class 10-32 neg. 10-32 neg. neg. 10-32 neg. Protection class (with connected cable) EN 60529 IP65 Case material DIN 1,4542 Weight g 13 19 19 2.5 16 Tightening torque, max., MA N·m 0.2 0.2 0.2 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 2 0.5	of sensitivity, F _z	% / °C	≈–0,01	≈-0,02	≈–0,02	≈<0,04	≈<0,04
Connection KIAG 10-32 neg. MID-32 neg. KIAG 10-32 neg. KIAG 10-32 neg. MID-32 neg. KIAG 10-32 neg. KIAG 10-32 neg. MID-32 neg.	Insulation resistance at 20 °C	Ω			>10 ¹³		
To-32 neg. 10-32 neg. 10-	Capacity C	pF	≈22	≈26	≈26	≈15	≈45
Protection class (with connected cable) EN 60529 IP65 Case material DIN 1,4542 Weight g 13 19 19 2.5 16 Tightening torque, max., MA M2 N·m 0.2 0.2 0.2 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 2 0.2 0.5	Connection	·	KIAG	KIAG	KIAG	M4x0.35	KIAG
(with connected cable) EN 60529 IP65 Case material DIN 1,4542 Weight g 13 19 19 2.5 16 Tightening torque, max., MA N·m 0.2 0.2 0.2 0.5 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 2 0.2 0.5			10-32 neg.	10-32 neg.	10-32 neg.	neg.	10-32 neg.
Case material DIN 1,4542 Weight g 13 19 19 2.5 16 Tightening torque, max., MA N·m 0.2 0.2 0.2 0.5 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 2 0.2 0.5	Protection class						
Weight g 13 19 19 2.5 16 Tightening torque, max., MA N·m 0.2 0.2 0.2 0.5 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 2 0.2 0.2	(with connected cable)	EN 60529			IP65		
Tightening torque, max., MA N·m 0.2 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 2 2 0.5	Case material	DIN			1,4542		
Tightening torque, max., MA N·m 0.2 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 2 2 0.5	Weight	g	13	19	19	2.5	16
M2 N·m 0.2 M3 N·m 0.5 0.2 0.2 0.5 M5x0.5 N·m 2 2	Tightening torque, max., M _A						
M5x0.5 N·m 2		N⋅m				0.2	
	M3	N⋅m	0.5	0.2	0.2		0.5
M10x1 N·m 10 10 10 10	M5x0.5	N⋅m				2	
· · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · · ·	M10x1	N⋅m	10	10	10		10

¹⁾ Application of force on the flange level



Dimensions

Dimensions of Type 9203

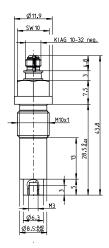


Fig. 1: Dimensions of sensor for small forces Type 9203

Dimensions of Type 9207

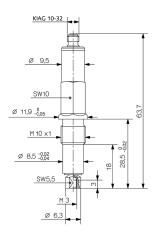
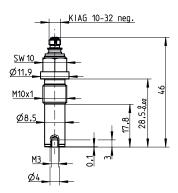


Fig. 3: Dimensions of sensor for small forces Type 9207

Dimensions of Type 9217A



Dimensions of Type 9205

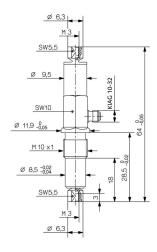


Fig. 2: Dimensions of sensor for small forces Type 9205

Dimensions of Type 9215A

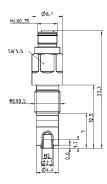


Fig. 4: Dimensions of sensor for small forces Type 9215A

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Mounting Examples

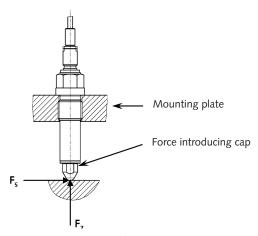


Fig. 6: Force application on force introducing cap

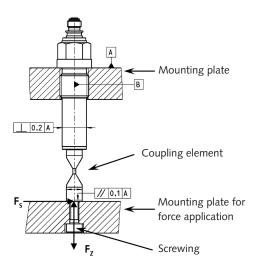


Fig. 7: Mounting with coupling element

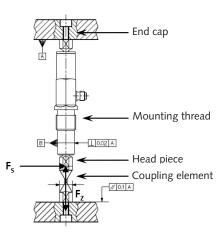


Fig. 8: Mounting of Type 9205 between two plates with coupling element

Accessories

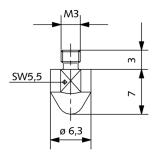


Fig. 9: Force introducing cap Art. No. 3.220.139 for Type 9203, 9205, 9207, and 9217A

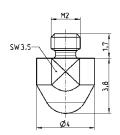


Fig. 10: Force introducing cap Art. No. 3.220.217 for Type 9215A

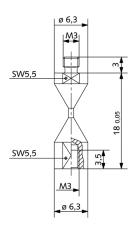


Fig. 11: Coupling element Type 9405 for Type 9203, 9205, 9207, and 9217A



Optional Accessories		Ordering Code	
Force introducing cap	Type 3.220.139	Highly sensitive force sensor	Type 9203
Coupling element	9405	M10x1, axial connection, –500 500 N	9203
for Type 9203, 9205, 9207, and 9217A	J+03	Sensor for small forces	9205
• Connecting cable KIAG 10-32 pos. – BNC pos.		M10x1, radial connection, –50 50 N	3203
Length 1 m	1631C1	Sensor for small forces	9207
Length 2 m	1631C2	M10x1, axial connection, –50 50 N	
Length 5 m	1631C5	Sensor for small forces	9215A
Length 10 m	1631C10	M5x0.5, axial connection, –20 200 N	
Fluoropolymer connecting cable, oil-proof		• Sensor for small tensile and compression forces	9217A
for Type 9203, 9205, 9207, 9217A		M10x1, axial connection, -500 500 N	
KIAG 10-32 pos. int. – BNC pos.			
Length 2 m	1983AD2		
Length 5 m	1983AD5		
 Connecting cable M4x0.35 pos. – BNC pos. 			
for Type 9215A			
Length 1 m	1651C1		
Length 2 m	1651C2		
Length 5 m	1651C5		
Length 10 m	1651C10		
Fluoropolymer connecting cable, oil-proof			
for Type 9215A			
M4x0.35 pos. int. – KIAG 10-32 pos. int			
Length 1 m	1983AB1		
Length 2 m	1983AB2		
Length 3 m	1983AB3		
Length 5 m	1983AB5		
Coupling	1729A		
for Type 9203, 9205, 9207, 9217A			
KIAG 10-32 neg. – KIAG 10-32 neg.			
Angle coupling	1700A29		
for Type 9203, 9205, 9207, 9217A			
KIAG 10-32 pos. int. – KIAG 10-32 neg.			
 Cleaning and insulation spray 250 ml 	1003		
 Insulation testing device 	5493		
For connection, extension, and connecting cable	es, see da-		

For connection, extension, and connecting cables, see data sheet for Cables for Force, Torque, and Strain Sensors (1631C_000-346).

For cable connectors, couplings, and accessories, see data sheet for Coaxial Cable Connectors (1700_000-347).