DURA IIIPULSE

Dynamic Braking User Manual GS-DB_UMW





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~ WARNING ^

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WARNING: ALWAYS READ THIS MANUAL THOROUGHLY BEFORE USING THE DURAPULSE DYNAMIC BRAKE UNIT WITH THE DURAPULSE AC MOTOR DRIVE.



WARNING: AC INPUT POWER MUST BE DISCONNECTED BEFORE PERFORMING ANY MAINTENANCE. DO NOT CONNECT OR DISCONNECT WIRES OR CONNECTORS WHILE POWER IS APPLIED TO THE CIRCUIT. MAINTENANCE MUST ONLY BE PERFORMED BY A QUALIFIED TECHNICIAN.



WARNING: THERE ARE HIGHLY SENSITIVE MOS COMPONENTS ON THE PRINTED CIRCUIT BOARDS. THESE COMPONENTS ARE ESPECIALLY SENSITIVE TO STATIC ELECTRICITY. TO AVOID DAMAGE TO THESE COMPONENTS, DO NOT TOUCH THESE COMPONENTS OR THE CIRCUIT BOARDS WITH METAL OBJECTS OR YOUR BARE HANDS.



WARNING: A CHARGE MAY STILL REMAIN IN THE AC DRIVE'S DC-LINK CAPACITOR(S) WITH HAZARDOUS VOLTAGES EVEN IF THE POWER HAS BEEN TURNED OFF TO THE AC DRIVE. TO AVOID PERSONAL INJURY, DO NOT REMOVE THE COVER OF THE DURAPULSE DYNAMIC BRAKE UNIT OR THE AC DRIVE UNTIL THE POWER HAS BEEN DISCONNECTED FROM THE AC DRIVE AND ALL "DISCHARGE" INDICATORS ON THE DEVICES ARE OFF. PLEASE NOTE THAT THERE ARE LIVE COMPONENTS EXPOSED WITHIN THE BRAKE UNIT AND THE AC DRIVE. DO NOT TOUCH THESE LIVE PARTS.



WARNING: GROUND THE DURAPULSE DYNAMIC BRAKE UNIT USING THE GROUND TERMINAL. THE GROUNDING METHOD MUST COMPLY WITH THE LAWS OF THE COUNTRY WHERE THE BRAKE UNIT IS TO BE INSTALLED. REFER TO THE "BASIC BRAKING WIRING DIAGRAM" SHOWN IN "CHAPTER 3: COMPONENT CONFIGURATION AND WIRING."



WARNING: THE MOUNTING ENCLOSURE OF THE DURAPULSE DYNAMIC BRAKE UNIT MUST COMPLY WITH EN50178. Live parts shall be arranged in enclosures or located behind barriers that meet at least the requirements of the Protective Type IP20. The top surface of the enclosures or barrier that is easily accessible shall meet at least the requirements of the Protective Type IP40. Users must provide this environment for the brake unit and braking resistor.



DURAPULSE DYNAMIC BRAKING USER MANUAL REVISION HISTORY



Please include the Manual Number and the Manual Issue, both shown below, when communicating with Technical Support regarding this publication.

MANUAL NUMBER:	GS-DB_UMW
ISSUE:	Second Edition, Revision D
ISSUE DATE:	06/10/2022

	PUBLICATION HISTORY								
ISSUE	DATE	DESCRIPTION OF CHANGES							
First Edition	11/17/2003	Original							
1st Ed. Rev.A	03/2004	Minor changes							
1st Ed. Rev.B	07/2009	GS-2050-BR-ENC specifications							
Second Edition	09/28/2017	User Manual name change (previous name: GS3-DB-M) Added GS4 series AC Drives Added (5) GS-xDB series Dynamic Braking Units; where x = 1,3,5,6,7 Added (19) GS-BR-xxxWxxx series Dynamic Braking Resistors Added Chapters 2 and 3 Modifications to braking resistor dimension drawings Ch2							
2nd Ed. Rev.A	10/26/2017	Bar code Ch2: Dimensions for resistors GS-20P5-BR & GS-21P0-BR							
2nd Ed. Rev.B	05/17/2019	User Manual name change (previous name: GS-DB_UMP) Ch3: Thermal overload relay recommendation and wiring diagram							
2nd Ed. Rev.C	06/14/2019	Ch3: Basic Braking Wiring Diagram							
2nd Ed., Rev. D	06/10/2022	Ch1 and Ch2: Added new braking resistors for GS20 drives							

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MANUAL OVERVIEW

OVERVIEW OF THIS PUBLICATION

The *DURAPULSE* Dynamic Braking User Manual describes the installation, wiring, configuration, and operation of the dynamic braking unit and braking resistors as used with GS3 and GS4 series *DURAPULSE* AC Drives.

The content of this user manual may be revised without prior notice. Please visit the Automationdirect.com website to download the most recent version. (www.automationdirect.com)

WHO SHOULD READ THIS MANUAL

This manual contains important information for those who will install, maintain, and/or operate any *DURAPULSE* GS3 or GS4 series AC Drive that makes use of the dynamic braking in their application.

SUPPLEMENTAL PUBLICATIONS

The *DURAPULSE* AC Drive User Manuals (GS3-M & GS4-M) are available from AutomationDirect and should be used along with this manual to properly install and operate both the *DURAPULSE* AC drive and the *DURAPULSE* dynamic braking unit.

The National Electrical Manufacturers Association (NEMA) publishes many different documents that discuss standards for industrial control equipment. Global Engineering Documents handles the sale of NEMA documents. For more information, you can contact Global Engineering Documents at:

15 Inverness Way East Englewood, CO 80112-5776 1-800-854-7179 (within the U.S.) 303-397-7956 (international) www.global.ihs.com

NEMA documents that might assist with your AC drive systems are:

- Application Guide for AC Adjustable Speed Drive Systems
- Safety Standards for Construction and Guide for Selection, Installation, and Operation of Adjustable Speed Drive Systems

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SPECIAL SYMBOLS



When you see the "notepad" icon in the left-hand margin, the paragraph to its immediate right will be a special note.



When you see the "exclamation mark" icon in the left-hand margin, the paragraph to its immediate right will be a warning. This information could prevent injury, loss of property, or even death (in extreme cases).

INTRODUCTION

DYNAMIC BRAKING

All *DURAPULSE* GS3 and GS4 series AC drives are capable of dynamic braking to enable an AC motor with a high-inertia load to decelerate more rapidly than could be otherwise achieved, and to absorb the energy generated when a three-phase induction motor decelerates.

Applications with high-inertia type loads tend to cause the motor to regenerate energy back into the AC drive. This regeneration causes the AC drive's internal DC bus voltage to rise, which can cause an over voltage fault. With dynamic braking, the energy generated by the overhauling motor is dissipated through dedicated braking resistors as heat.

As shown in the selection tables in this chapter, lower-capacity drives can connect directly to the optional external braking resistors, but higher-capacity drives also require optional dynamic braking units installed between the drives and resistors.

DYNAMIC BRAKING UNITS

DURAPULSE dynamic braking units are used with larger DURAPULSE AC Drives to continuously monitor the drive's DC bus voltage. When bus voltage exceeds a predetermined level (depending on the supply voltage) the dynamic braking unit dissipates the excess energy into external resistors in the form of heat. DURAPULSE dynamic braking units must be used along with GS series braking resistors to provide optimum braking performance.

DURAPULSE dynamic braking units are available for both 230V or 460V *DURAPULSE* AC Drives. MASTER/SLAVE configurations allow the use of multiple *DURAPULSE* dynamic braking units in order to accommodate the power ratings of larger *DURAPULSE* AC Drives and motors.

DURAPULSE dynamic braking units (GS-1DBU, GS-2DBU, GS-3DBU and GS-4DBU) are approved by Underwriters Laboratories, Inc. (UL) and Canadian Underwriters Laboratories (cUL).

Unpacking

After receiving the DURAPULSE dynamic braking unit, please check for the following:

- Make sure that the part number indicated on the package corresponds with the part number of your order.
- Make sure that the package includes the *DURAPULSE* dynamic braking unit and the *DURAPULSE* dynamic braking unit User Manual.
- Inspect the contents to insure they were not damaged during shipment.

BRAKING DUTY CYCLE

Application of a DURAPULSE dynamic braking unit should take into account how often the motor will stop or decelerate during normal operation. The Duty Cycle is the percentage of time the brake is actually used during deceleration in comparison to the time elapsed between each start or acceleration of the motor. This Duty Cycle percentage is necessary to allow the dynamic braking unit and braking resistor(s) sufficient time to dissipate the heat created during dynamic braking. If the Duty Cycle is exceeded, the braking resistor will not cool sufficiently, causing resistance to increase as the temperature rises with the loss of effective braking torque.

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Example: If in a given application it is determined that it will take 10 seconds for the motor to decelerate to a stop using dynamic braking, then the motor can only be cycled on and off continuously every 1.6 minutes (100 seconds).



10 / 100 x 100 = 10% Duty Cycle

The maximum braking On-Time for the maximum 10% Duty Cycle is 10 seconds.



OVERLOAD RELAY

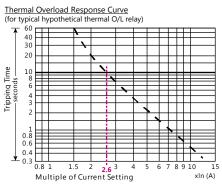
OVERLOAD RELAY PURPOSE

For safety purposes, install an external overload relay between the dynamic brake unit and the braking resistor. The thermal overload relay protects the braking resistor from damage due to frequent braking, or due to the braking unit operating excessively due to unusually high input voltage.

OVERLOAD RELAY SELECTION PROCEDURE AND EXAMPLE

(For a GS4-4150 drive)

1) Select a thermal overload relay based on its overload capability.



Standard braking capacity for GS3 and GS4 AC drives is 10% duty cycle (tripping time = 10s). Determine the 10s Overload Capacity (Multiple of Current Setting) for your selected overload relay. The intersection of the Trip Time

(10s) and the Multiple of Current Setting is 2.6 (or 260%) for this example response curve. The property of each thermal

relay may vary by manufacturer, so please read the specifications carefully.

2) Use the appropriate AC Drive Braking Component Selection table in this chapter to find the Max Total Brake Current for the motor, drive, and braking components (126A for this example).

GS <u>4</u> AC DRIVE BRAKING COMPONENT SELECTION														
	MOTOR POWER		125% BRAKING TORQUE @ 10% DUTY CYCLE							CLE	MAX BRAKING TORQUE			
VOLTAGE			Power		ODEL		RAKING UNIT		BRAKING RESISTOR	QUE	ake (A)	ror ()	BRAKE (A)	(MX)
DRIVE V	(нР)	(м)	AC DRIVE MODEL # GS4-	QUANTITY	PART # GS-	QUANTITY	PART # GS-BR-	BRAKE TORQUE (KG·M)	TOTAL BRAKE CURRENT (A)	MIN RESISTOR VALUE (Ω)	4X TOTAL E CURRENT	PEAK POWER (KW)	WIRING	
			AC	gu	а	ď	40	BI	- 0	2	MA	PEA		
460V	150	110	4150	1	5DBU	10	1K2W015	74.5	126	6.0	126	95.8	L	
4														

3) Divide the Max Total Braking Current by the Overload Capacity (126A / 2.6 = 48.46A), and select a thermal O/L relay which has the same or higher rated current. In this case, select a 50A relay.



For wiring information, refer to "Overload Relay" in Chapter 3, page 3-2.

DYNAMIC BRAKING COMPONENT SELECTION FOR DURAPULSE AC DRIVES

The following table provides the selection information for the *DURAPULSE* dynamic braking units designed for use with GS3 and GS4 series AC drives.

BRAKING COMPONENT SELECTION FOR GS3 DURAPULSE DRIVES

NOTE: For breaking resistor compatibility with other Automation Direct VFDs (GS10, GS20, ACN) consult the user manual Appendix A for each VFD. For WEG CFW drives, consult the Automation direct technical pages.

GS <u>3</u> AC Drive Braking Component Selection															
			12	5% E	BRAKING	Tor	QUE @ 10% DU	TY CYCLE**	**	MAX E	RAKING	TORQUE	*		
DLTAGE		TOR NER	AC Drive	B	raking Unit		BRAKING RESISTOR		TOTAL BRAKE	MIN RESIS-	MAX TOTAL		IGRAM		
DRIVE VOLTAGE			MODEL #	QUANTITY	PART #	QUANTITY	PART #	BRAKE TORQUE	CUR- RENT	TOR VALUE	BRAKE CUR- RENT	PEAK POWER	WIRING DIAGRAM		
	(нр)	(ĸW)	GS3-	8	GS-	8	GS-	(кс•м)	(A)	(Ω)	(A)	(W)	ž		
	1	0.7	21P0			1	21P0-BR	0.5	1.9	82	4.6	1.8			
	2	1.5	22P0	1		1	22P0-BR	1.0	3.8	82	4.6	1.8			
	3	2.2	23P0	1		1	23P0-BR	1.5	5.4	82	4.6	1.8			
	5	3.7	25P0	0	n/a	1	25P0-BR	2.5	9.5	33	11.5	4.4	A		
	7.5	5.5	27P5	1		1	27P5-BR	3.7	12.7	30	12.7	4.8	1		
230V	10	7.5	2010	1		1	2010-BR-ENC	5.1	19.0	20	19.0	7.2			
23	15	11	2015	1		1	2015-BR-ENC	7.5	27.9	13.6	27.9	10.6			
	20	15	2020	1	2DBU	1	2020-BR-ENC	10.2	38.0*	10*	38.0*	14.4*			
	25	18	2025	1	2DBU	1	2025-BR-ENC	12.2	47.5*	8*	47.5*	18.1*	D		
	30	22	2030	1	2DBU	1	2030-BR-ENC	14.9	55.9*	6.8*	55.9*	21.2*			
	40	30	2040	2	2DBU	2	2040-BR-ENC	20.3	38.0*	10*	38.0*	14.5*	F		
	50	37	2050	2	2DBU	2	2050-BR-ENC	25.1	47.5*	8*	47.5*	18.1*	F		
	1	0.7	41P0			1	41P0-BR	0.5	1.0	160	4.8	3.6			
	2	1.5	42P0			1	42P0-BR	1.0	1.9	160	4.8	3.6			
	3	2.2	43P0			1	43P0-BR	1.5	3.0	160	4.8	3.6			
	5	3.7	45P0	0	n/a	1	45P0-BR	2.5	5.1	130	5.8	4.4	A		
	7.5	5.5	47P5					1	47P5-BR	3.7	7.6	91	8.4	6.3	
	10	7.5	4010			1	4010-BR	5.1	10.1	62	12.3	9.3			
>	15	11	4015			1	4015-BR-ENC	7.5	15.2	39	19.5	14.8			
460V	20	15	4020	1	4DBU	1	4020-BR-ENC	10.2	19.0*	40*	19.0*	14.4*			
4	25	18	4025	1	4DBU	1	4025-BR-ENC	12.2	23.8*	32*	23.8*	18.1*			
	30	22	4030	1	4DBU	1	4030-BR-ENC	14.9	27.9*	27.2*	27.9*	21.2*	D		
	40	30	4040	1	4DBU	1	4040-BR-ENC	20.3	38.0*	20*	38.0*	28.9*	ש		
	50	40	4050	1	4DBU	1	4050-BR-ENC	25.1	47.5*	16*	47.5*	36.1*			
	60	45	4060	1	4DBU	1	4060-BR-ENC	30.5	55.9*	13.6*	55.9*	42.5*			
	75	55	4075	2	4DBU	2	4075-BR-ENC	37.2	38.0*	20*	38.0*	28.9*	F		
	100	75	4100	2	4DBU	2	4100-BR-ENC	50.8	55.9*	13.6*	55.9*	42.5*	Г		
* 7	75 100	55 75	4075 4100	2 2	4DBU 4DBU	2 2	4075-BR-ENC	37.2 50.8	38.0* 55.9*	20* 13.6*	38.0*	28.9*	-		

* These values are per individual DBU, as seen between DBU terminals B1 and B2.

** Wiring diagrams are shown in Chapter 3: Component Configuration and Wiring.

*** 10% Duty Cycle with maximum ON (braking) time of 10 seconds.

BRAKING COMPONENT SELECTION FOR GS4 DURAPULSE DRIVES

GS4 AC DRIVE BRAKING COMPONENT SELECTION																					
			125	% В	RAKING T	ORQU	IE @ 10% DU	TY CYCLE*	**	MAX B	RAKING	TORQUE	*								
DLTAGE	Mo Pov	TOR NER	AC Drive		RAKING UNIT	1	BRAKING RESISTOR		TOTAL BRAKE	Min Resis-	MAX TOTAL		GRAM								
DRIVE VOLTAGE			MODEL #	QUANTITY	PART #	QUANTITY	PART #	BRAKE TORQUE	CUR- RENT	tor Value	BRAKE CUR- RENT	PEAK POWER	WIRING DIAGRAM								
	(нр)	(ĸW)	GS4-	ď	GS-	'n	GS-BR-	(кс•м)	(A)	(Ω)	(A)	(ĸW)	WIF								
	1	0.7	21P0			1	080W200	0.5	1.9	63.3	6	2.3									
	2	1.5	22P0	1		1	200W091	1.0	4.2	47.5	8	3.0									
	3	2.2	23P0	1		1	300W070	1.5	5.4	38.0	10	3.8									
	5	3.7	25P0	1		1	400W040	2.5	9.5	19.0	20	7.6	A								
	7.5	5.5	27P5		,	1	1KOW020	3.7	19	14.6	26	9.9									
	10	7.5	2010	0	n/a	1	1K0W020	5.1	19	14.6	26	9.9									
	15	11	2015	1		1	1K5W013	7.5	29	12.6	28	10.6									
230V	20	15	2020]		2	1KOW4P3	10.2	44	8.3	46	17.5									
	25	18	2025	1		2	1KOW4P3	12.2	44	8.3	46	17.5	В								
	30	22	2030]		2	1K5W3P3	14.9	58	5.8	66	25.1									
	40	30	2040	2	1DBU	4	1K0W5P1	20.3	75*	4.8*	80*	30.4*									
	50	37	2050	2	2DBU	4	1K2W3P9	25.1	97*	3.2*	120*	45.6*	G								
	60	45	2060	2	2DBU	4	1K5W3P3	30.5	118*	3.2*	120*	45.6*									
	75	55	2075	3	2DBU	6	1K2W3P9	37.2	145*	2.1*	180*	68.4*	J								
	100	75	2100	4	2DBU	8	1K2W3P9	50.8	190*	1.6*	240*	91.2*	К								
	1	0.7	41P0											1	080W750	0.5	1	190	4	3.0	
	2	1.5	42P0			1	200W360	1	2.1	126.7	6	4.6									
	3	2.2	43P0			1	300W250	1.5	3	108.6	7	5.3									
	5	3.7	45P0			1	400W150	2.5	5.1	84.4	9	6.8	A								
	7.5	5.5	47P5			1	1K0W075	3.7	10.2	54.3	14	10.6									
	10	7.5	4010	0	n/a	1	1K0W075	5.1	10.2	47.5	16	12.2									
	15	11	4015			1	1K5W043	7.5	17.6	42.2	18	13.7									
	20	15	4020			2	1KOW016	10.2	24	26.2	29	22.0									
	25	18	4025			2	1KOW016	12.2	24	23.0	33	25.1	В								
>	30	22	4030			2	1K5W013	14.9	29	23.0	33	25.1									
460V	40	30	4040			4	1KOW016	20.3	47.5	14.1	54	41.0	С								
	50	40	4050	1	4DBU	4	1K2W015	25.1	50*	12.7*	60*	45.6*	E								
	60	45	4060	1	4DBU	4	1K5W013	30.5	59*	12.7*	60*	45.6*									
	75	55	4075	2	3DBU	8	1KOW5P1	37.2	76*	9.5*	80*	60.8*	н								
	100	75	4100	2	4DBU	8	1K2W015	50.8	100*	6.3*	120*	91.2*									
	125	90	4125	2	4DBU	8	1K5W013	60.9	117*	6.3*	120*	91.2*									
	150	110	4150	1	5DBU	10	1K2W015	74.5	126*	6.0*	126*	95.8*	L								
	175	132	4175	1	6DBU	12	1K5W012	89.4	190*	4.0*	190*	144.4*	м								
	200	160	4200	1	6DBU	12	1K5W012	108.3	190*	4.0*	190*	144.4*									
	250	185	4250	1	7DBU	14	1K5W012	125.3	225*	3.4*	225*	172.1*	Ν								
	300	220	4300	2	5DBU	20	1K2W015	148.9	252*	3.0*	252*	190.5*	0								
* T	* These values are per individual DBU, as seen between DBU terminals B1 and B2.																				

** Wiring diagrams are shown in Chapter 3: Component Configuration and Wiring.

*** 10% Duty Cycle with maximum ON (braking) time of 10 seconds.

DYNAMIC BRAKING UNIT SPECIFICATIONS

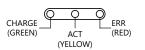
The following table provides the specifications and applications for the *DURAPULSE* dynamic braking units designed for use with GS3 and GS4 series AC drives.

	Dynam	ic Braki	ng Unit S	PECIFICA	TIONS				
BRA	KING UNIT PART NUMBER	GS- 1DBU	GS- 2DBU	GS- 3DBU	GS- 4DBU	GS- 5DBU	GS- 6DBU	GS- 7DBU	
Non	IINAL VOLTAGE (VAC)		2080 230	3080	4060	460	6DBU	7060	
MAX MOTOR CAPACITY (HP/[KW])			30	40	60	150	200	250	
NIA.		[15]	[22]	[30]	[45]	[110]	[160]	[185]	
TING	MAX DISCHARGE CURRENT (A) @ 10% DUTY CYCLE*	40	60	40	60	126	190	225	
8	CONTINUOUS DISCHARGE CURRENT (A)	15	20	15	18	45	50	100	
OUTPUT RATING	BRAKING STARTUP VOLTAGE (VDC)		45/360/ 0/415 ±3V		90/720/ 0/830 ±6V		/642/667/ 25/750 ±6		
0	MAXIMUM ON-TIME (S)				10				
INPL	IT DC VOLTAGE (VDC)	200)-415	400	0–830		400-750		
	EQUIVALENT RESISTOR EACH BRAKING UNIT (Ω)	10	6.8	20	13.6	6	4	3.4	
>	Power CHARGE LAMP/LED		nes ON unti P – -N) drop:		Comes ON when DC bus voltage (DC+ – DC-) rises above 300VDC. Goes OFF when DC bus voltage (DC+ – DC-) drops below 100VDC.				
02	BRAKING ACT LAMP/LED	ON during braking							
PROTECTION	FAULT ERR LAMP	ON if	an over-tem occu	perature	n/a				
٩	OVERCURRENT LEVEL LED (A)		n,	/a	190 290 340				
	OVERHEAT LED		n,	/a			ON > 176°)FF < 149°F		
	HEAT SINK OVERHEAT TEMPERTURE		203°F	[95°C]		n/a			
	ALARM OUTPUT RELAY CONTACT	5A @	2 120VAC/2	8VDC (RA,	RB,RC)	3A @	250VAC/2 (RA,RC)	8VDC	
ž	INSTALLATION LOCATION		indoor	(no corro	sive gases; i	no metallio	dust)		
ENVIRONMENT	OPERATING TEMPERATURE				22 °F [-10 t		-		
ð	STORAGE TEMPERATURE				40 °F [-20 to				
N	Ниміріту	less than 90% RH, non-condensing							
-	VIBRATION	9.8 m/s ² [1G] under 20Hz ; 2m/s ² [0.2G] at 20–50 Hz							
	HANICAL CONFIGURATION		P50 wall-mc		sed	IP10 wa	III-mount e	nclosed	
* 10	% Duty Cycle with maximum ON (brak	ing) time (of 10 second:	s					

LAMP/LED INDICATORS FOR DYNAMIC BRAKING UNITS

GS-1DBU, GS-2DBU, GS-3DBU, GS-4DBU

GS-5DBU, GS-6DBU, GS-7DBU





See "DBU Jumper and Wiring Terminal Locations" in Chapter 3 for locations of indicators.

DYNAMIC BRAKING RESISTORS SPECIFICATIONS

BRAKING RESISTOR SPECIFICATIONS									
PART NUMBER	Power (W)	RESISTANCE (Ω)	ΤΥΡΕ	DIMENSION DRAWING # (SEE CHAPTER 2)					
GS-20P5-BR	80	200		1					
GS-21PO-BR	80	200		1					
GS-22PO-BR	300	100	onon	1					
GS-23PO-BR	300	70	open	1					
GS-25PO-BR	400	40		1					
GS-27P5-BR	500	30		2					
GS-2010-BR-ENC	1000	20		4					
GS-2015-BR-ENC	2400	13.6		5					
GS-2020-BR-ENC	3000	10		5					
GS-2025-BR-ENC	4800	8	enclosed	6					
GS-2030-BR-ENC	4800	6.8		6					
GS-2040-BR-ENC	3000	10		5					
GS-2050-BR-ENC	4800	8		6					
GS-41PO-BR	80	750		1					
GS-42PO-BR	300	400		1					
GS-43PO-BR	300	250		1					
GS-45PO-BR	400	150	open	1					
GS-47P5-BR	500	100		2					
GS-4010-BR	1000	75		3					
GS-4015-BR-ENC	1000	50		4					
GS-4020-BR-ENC	1500	40		7					
GS-4025-BR-ENC	4800	32		8					
GS-4030-BR-ENC	4800	27.2		8					
GS-4040-BR-ENC	6000	20	enclosed	8					
GS-4050-BR-ENC	9600	16		9					
GS-4060-BR-ENC	9600	13.6		9					
GS-4075-BR-ENC	6000	20		8					
GS-4100-BR-ENC	9600	13.6		9					
GS-BR-080W200	80	200		10					
GS-BR-080W750	80	750		10					
GS-BR-200W091	200	91		10					
GS-BR-200W360	200	360		10					
GS-BR-300W070	300	70		10					
GS-BR-300W250	300	250	open	10					
GS-BR-300W400	300	400		10					
GS-BR-400W040	400	40		10					
GS-BR-400W150	400	150		10					
GS-BR-500W100	500	100		2					
GS-BR-750W140	750	140		12					

Chapter 1: Overview and Component Specifications

VAUTOMATIONDIRECT

BRAKING RESISTOR SPECIFICATIONS (CONTINUED)								
PART NUMBER	Power (W)	Resistance (Ω)	ΤΥΡΕ	DIMENSION DRAWING # (SEE CHAPTER 2)				
GS-BR-1KOW4P3	1000	4.3		11				
GS-BR-1KOW5P1	1000	5.1		11				
GS-BR-1K0W016	1000	16		11				
GS-BR-1K0W020	1000	20		11				
GS-BR-1K0W075	1000	75		11				
GS-BR-1K2W3P9	1200	3.9	open	11				
GS-BR-1K2W015	1200	15		11				
GS-BR-1K5W3P3	1500	3.3		11				
GS-BR-1K5W012	1500	12		11				
GS-BR-1K5W013	1500	13		11				
GS-BR-1K5W043	1500	43		11				



BRAKING COMPONENT INSTALLATION AND DIMENSIONS

TABLE OF CONTENTS

Installation	2–2
General Installation Guidelines	2–2
Minimum Clearances and Air Flow	2-2
Braking Unit Dimensions	2–4
Braking Resistor Dimensions.	2–5

INSTALLATION

GENERAL INSTALLATION GUIDELINES

Improper installation of the dynamic brake unit will greatly reduce its life. Be sure to observe the following precautions when selecting a mounting location.



WARNING: FAILURE TO OBSERVE THESE PRECAUTIONS MAY DAMAGE THE UNIT AND VOID THE WARRANTY!

- Do not mount the dynamic brake unit near heat-radiating elements or in direct sunlight.
- Do not install the dynamic brake unit in a place subjected to high temperatures, high humidity, excessive vibration, corrosive gasses or liquids, or airborne dust or metallic particles.
- Mount the dynamic brake unit vertically and do not restrict the air flow to the heat sink fins.



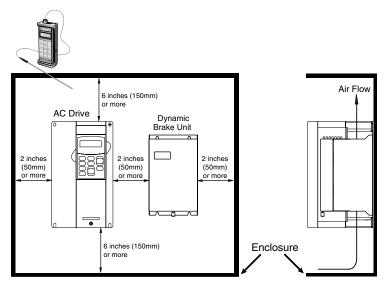
WARNING: THE DYNAMIC BRAKE UNIT AND BRAKING RESISTORS GENERATE LARGE AMOUNTS OF HEAT WHICH MAY DAMAGE THE BRAKING UNIT, RESISTORS, OR ANY EQUIPMENT MOUNTED IN THE SAME ENCLOSURE AS THE HEAT PRODUCING DEVICES. AUXILIARY COOLING METHODS ARE TYPICALLY REQUIRED SO AS NOT TO EXCEED MAXIMUM AMBIENT TEMPERATURES, ESPECIALLY IF FREQUENT DECELERATION BRAKING IS PERFORMED (OVER 10% DUTY CYCLE).



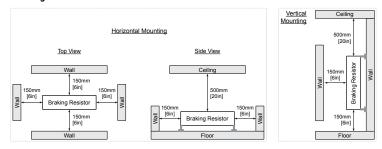
WARNING: FLAMMABLE SOLIDS, GASES, OR LIQUIDS MUST BE AVOIDED AT LOCATIONS WHERE BRAKING RESISTORS ARE INSTALLED. IDEALLY, BRAKING RESISTORS SHOULD BE INSTALLED IN INDIVIDUAL METALLIC BOXES WITH FORCED AIR-COOLING.

MINIMUM CLEARANCES AND AIR FLOW

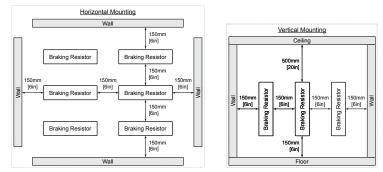
Minimum Clearances for Drives and Dynamic Braking Units



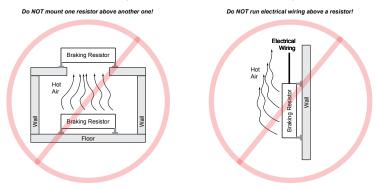
Minimum Clearances for Braking Resistors Mounting Individual Resistors



Mounting Multiple Resistors

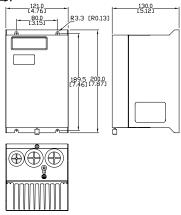


Do NOT Mount Heat-Producing or Heat-Sensitive Items Above Braking Resistors

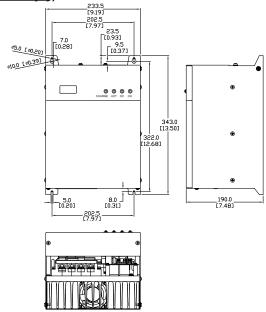


BRAKING UNIT DIMENSIONS

A) DBU ≤ 100hp (GS-1DBU, GS-2DBU, GS-3DBU, GS-4DBU) (<u>Dimensions = mm [in]</u>)



B) DBU > 100hp (GS-5DBU, GS-6DBU, GS-7DBU) (<u>Dimensions = mm [in]</u>)

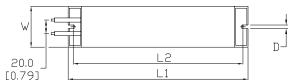


BRAKING RESISTOR DIMENSIONS

Braking Resister Dimension Drawing Index									
RESISTOR	#	RESISTOR	#	Γ	RESISTOR	#	Γ	RESISTOR	#
GS-20P5-BR	1	GS-41PO-BR	1		GS-BR-080W200	10]	GS-BR-1K0W4P3	11
GS-21PO-BR	1	GS-42P0-BR	1		GS-BR-080W750	10]	GS-BR-1K0W5P1	11
GS-22PO-BR	1	GS-43PO-BR	1		GS-BR-200W091	10		GS-BR-1K0W016	11
GS-23PO-BR	1	GS-45P0-BR	1		GS-BR-200W360	10		GS-BR-1K0W020	11
GS-25PO-BR	1	GS-47P5-BR	2]	GS-BR-300W070	10		GS-BR-1K0W075	11
GS-27P5-BR	2	GS-4010-BR	3		GS-BR-300W250	10]	GS-BR-1K2W3P9	11
GS-2010-BR-ENC	4	GS-4015-BR-ENC	4		GS-BR-300W400	10]	GS-BR-1K2W015	11
GS-2015-BR-ENC	5	GS-4020-BR-ENC	7		GS-BR-400W040	10		GS-BR-1K5W3P3	11
GS-2020-BR-ENC	5	GS-4025-BR-ENC	8		GS-BR-400W150	10		GS-BR-1K5W012	11
GS-2025-BR-ENC	6	GS-4030-BR-ENC	8]	GS-BR-500W100	2		GS-BR-1K5W013	11
GS-2030-BR-ENC	6	GS-4040-BR-ENC	8		GS-BR-750W140	12]	GS-BR-1K5W043	11
GS-2040-BR-ENC	5	GS-4050-BR-ENC	9]]		
GS-2050-BR-ENC	6	GS-4060-BR-ENC	9						
		GS-4075-BR-ENC	8						
		GS-4100-BR-ENC	9						

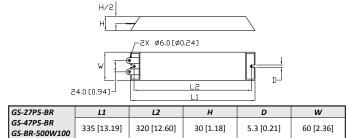
#1) GS-20P5-BR, GS-21P0-BR, GS-22P0-BR, GS-23P0-BR, GS-25P0-BR, GS-41P0-BR, GS-42P0-BR, GS-43P0-BR, GS-45P0-BR (<u>Dimensions = mm [in]</u>)

H/2

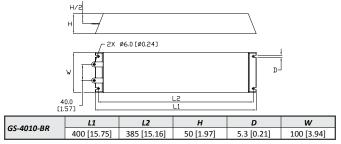


RESISTOR #	L1	L2	н	D	W
GS-20P5-BR		125 [4 02]	20 [0 70]		40 [1 [7]
GS-21PO-BR	140 [5.51]	125 [4.92]	20 [0.79]		40 [1.57]
GS-22PO-BR	215 [0.46]	200 [7 97]]	
GS-23PO-BR	215 [8.46]	200 [7.87]	30 [1.18]	5.3 [0.21]	60 [2.36]
GS-25PO-BR	265 [10.43]	250 [9.84]			
GS-41PO-BR	140 [5.51]	125 [4.92]	20 [0.79]		40 [1.57]
GS-42PO-BR	215 [0.46]	200 [7 97]			
GS-43PO-BR	215 [8.46]	200 [7.87]	30 [1.18]		60 [2.36]
GS-45PO-BR	265 [10.43]	250 [9.84]			

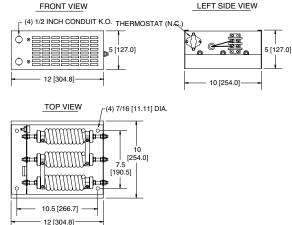


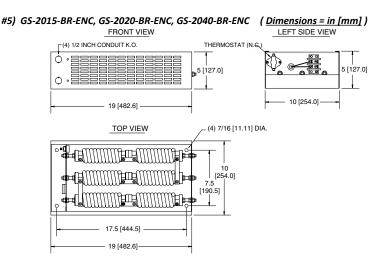


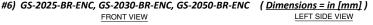


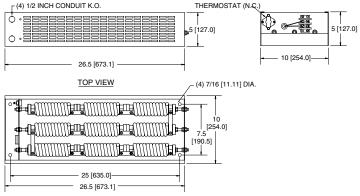


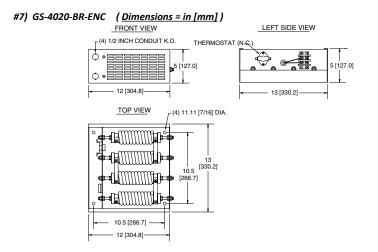




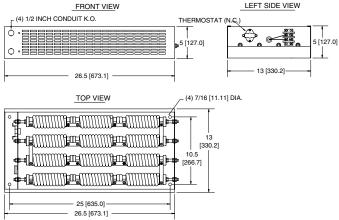


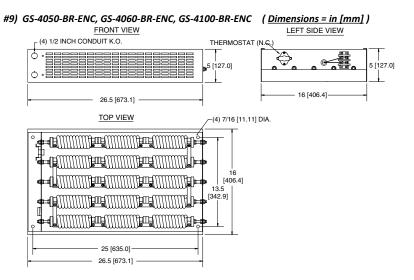




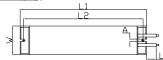


#8) GS-4025-BR-ENC, GS-4030-BR-ENC, GS-4040-BR-ENC, GS-4075-BR-ENC (<u>Dimensions = in [mm]</u>)



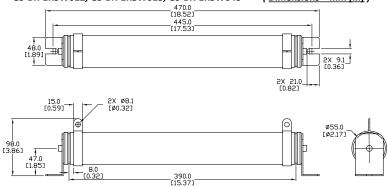


#10) GS-BR-080W200, GS-BR-080W750, GS-BR-200W091, GS-BR-200W360, GS-BR-300W070, GS-BR-300W250, GS-BR-400W040, GS-BR-400W150 (<u>Dimensions = mm [in]</u>)



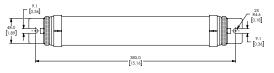
L3									
RESISTOR #	L1	L2	L3	W	Н	Α	L		
GS-BR-080W200	140	125	100	40.0	20.0				
GS-BR-080W750	[5.51]	[4.92]	[3.94]	[1.57]	[0.79]				
GS-BR-200W091	165	150	125						
GS-BR-200W360	[6.50]	[5.91]	[4.92]				200		
GS-BR-300W070	215	200	475	600	20.0	5.3 [0.21]	200 [7.87]		
GS-BR-300W250	215	200 [7.87]	175	60.0 [2.36]	30.0	[0.21]	[/.8/]		
GS-BR-300W400	[8.46]	[/.8/]	[6.89]	[2.30]	[1.18]				
GS-BR-400W040	265.34	250	225]					
GS-BR-400W150	[10.43]	[9.84]	[8.86]						

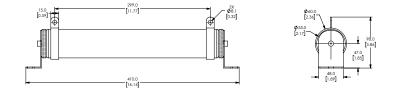
#11) GS-BR-1K0W4P3, GS-BR-1K0W5P1, GS-BR-1K0W016, GS-BR-1K0W020, GS-BR-1K0W075, GS-BR-1K2W3P9, GS-BR-1K2W015, GS-BR-1K5W3P3, GS-BR-1K5W012, GS-BR-1K5W013, GS-BR-1K5W043 (Dimensions = mm [in])



#12) GS-BR-750W140

(Dimensions = mm [in])







BRAKING COMPONENT CONFIGURATION AND WIRING

TABLE OF CONTENTS

OPERATIONAL ELECTRICAL INFORMATION

The *DURAPULSE* AC Drive and Dynamic Braking Unit will both be energized at the same time when power is applied to the drive. (Please refer to the applicable *DURAPULSE* AC Drive User Manual (GS3_UMW or GS4_UMW) to determine the start and stop operation of the motor.) The Dynamic Braking Unit will monitor the internal DC bus voltage of the AC drive. When the AC drive stops the motor by decelerating, the braking unit will detect an increase in the drive's DC bus voltage due to the motor causing regeneration. The braking unit will then dissipate this excess energy into the braking resistor in the form of heat. Dissipating this regenerated energy will allow a stable and controlled deceleration of the motor.

The alarm relay output contact terminals (RC, RA, & RB) of the dynamic braking unit will be activated when the temperature of the braking unit heat sink exceeds 203°F (95°C) for DBUs \leq 100hp, or 176°F (80°C) for DBUs > 100hp. This condition can be caused by the ambient temperature surrounding the braking unit exceeding 50°C (122°F), or by the Duty Cycle exceeding 10%. If this high ambient temperature situation exists, then a method of reducing the ambient temperature by the use of forced air cooling or some other means should be considered.

If the resistor does not have a temperature switch, install an overload relay between the DBU and the resistor.

OVERLOAD RELAY

For safety purposes, install an external overload relay between the dynamic braking unit and the braking resistor. Wire the overload relay normally closed contact in series with the coil of a magnetic contactor to interrupt the power to the AC drive.

The purpose of installing the thermal overload relay is to protect the braking resistor from damage due to frequent braking, or due to the braking unit operating excessively due to unusually high input voltage.

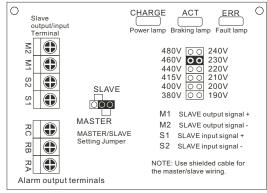


For overload relay selection information, refer to "Overload Relay Selection" in Chapter 1, page <u>1-5</u>.

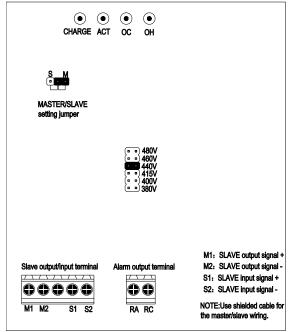
DYNAMIC BRAKING UNIT SETUP

DBU JUMPER AND WIRING TERMINAL LOCATIONS

DBU ≤ 100hp (GS-1DBU, GS-2DBU, GS-3DBU, GS-4DBU)



DBU > 100hp (GS-5DBU, GS-6DBU, GS-7DBU)



DBU VOLTAGE JUMPER SETTINGS

The power source for the *DURAPULSE* dynamic braking unit is DC bus voltage from the +(P) and -(N) terminals of the GS drive. It is important to set the voltage selection jumper of the *DURAPULSE* dynamic braking unit accurately based on the input power of the GS drive before operation. The voltage selection jumper setting determines the GS DC bus voltage level at which dynamic braking is applied.



Before setting the voltage selection jumper, make sure the power has been turned off. Set the jumper to match the highest possible voltage for an unstable power system.

Example: A 380VAC power system rises to 410VAC on a regular basis. To avoid engaging dynamic braking when the power supply voltage rises above 380VAC, set the voltage selection jumper to the 415VAC position.



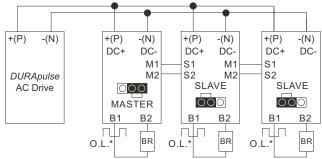
For DURApulse AC drives, set the "Over Voltage Stall Prevention" parameter as "close (1)" to disable over-voltage stall prevention (P6.05 in GS3; P6.11 in GS4). This will ensure a stable deceleration characteristic.

Braking Unit Voltage Settings								
	MODELS		MODELS > 100HP					
	(GS-1DBU, GS-2DBU		(GS-5DBU, GS-6DBU, GS-7DBU)					
23	OVAC CLASS	460VAC CLASS			460VAC CLASS			
AC Power Voltage	BRAKING START-UP VOLTAGE DC BUS (+(P), -(N)) VOLTAGE	AC Power Voltage	BRAKING START-UP VOLTAGE DC BUS (+(P), -(N)) VOLTAGE		AC Power Voltage	BRAKING START-UP VOLTAGE DC BUS (DC+,DC-) VOLTAGE		
190 VAC	330 VDC	380 VAC	660 VDC		380 VAC	618 VDC		
200 VAC	345 VDC	400 VAC	690 VDC		400 VAC	642 VDC		
210 VAC	360 VDC	415 VAC	720 VDC		415 VAC	667 VDC		
220 VAC	380 VDC	440 VAC	760 VDC		440 VAC	690 VDC		
230 VAC	400 VDC	460 VAC	800 VDC		460 VAC	725 VDC		
240 VAC	415 VDC	480 VAC	830 VDC		480 VAC	750 VDC		
NOTE: Input Power With Tolerance ±10%								

DBU MASTER/SLAVE JUMPER SETTINGS

The MASTER/SLAVE jumper on the *DURAPULSE* dynamic braking unit has a factory default setting as a MASTER. If the application of the *DURAPULSE* AC drive requires the use of more than one DBU, then the power terminals of the multiple units are wired in parallel and the first unit is set to MASTER while all remaining units are set to SLAVE. The jumper settings along with the wiring between the MASTER/SLAVE (M1, M2, S1 & S2) terminals allows the multiple braking units to synchronize the power dissipation between braking units. This assures each unit is dissipating an equivalent amount of energy to allow rapid deceleration of the motor.

Typical one-line wiring diagram for multiple parallel DURAPULSE dynamic braking units. The first DBU has the jumper set to MASTER, while the remaining DBUs are set to SLAVE. (DBU \leq 100hp have terminals +(P) & -(N); DBU > 100hp have terminals DC+ & DC-)



* Although it is recommended, the use of a thermal overload relay in line with the braking resistor is not required. GS-xxxx-BR-ENC braking resistors include a thermostat for thermal protection of the braking resistor, and are the preferred method of protection when available. Orient the braking resistors such that the thermostat is above the resistors in the enclosure, as this will ensure that the thermostat is exposed to the rising air temperature produced by the resistors. Refer to the "Basic Braking Wiring Diagram" on page <u>3–9</u> for details.

DYNAMIC BRAKING WIRING

WIRING WARNINGS AND NOTES



Do not proceed with any wiring while power is applied to the circuit, or while the drive or DBU charge LED(s) are on.



To prevent personal injury, do not connect/disconnect wires or regulate the setting of the braking unit while power on. Do not touch the terminals of related wiring and any component on PCB lest users be injured by extremely dangerous DC high voltage.



CONFIRM THAT THE +(P) AND -(N) TERMINALS OF THE DURAPULSE AC DRIVE ARE PROPERLY CONNECTED TO THE DURAPULSE DYNAMIC BRAKING UNIT WITH THE CORRECT POLARITY BEFORE APPLYING POWER. OTHERWISE, THE DRIVE AND THE BRAKING UNIT COULD BE DAMAGED.



Connect the braking unit ground terminal to Earth Ground. The ground lead must be the same gauge wire or larger than leads +(P) and -(N) or DC+ and DC-.



DO NOT WIRE TERMINALS -(N) OR DC- TO THE NEUTRAL POINT OF THE POWER SYSTEM.



DURING BRAKING, THE WIRES CONNECTED TO +(P), -(N), DC_+ , DC_- , B1, and B2 generate powerful electromagnetic fields due to high current passing through. Separate these wires from other low voltage control circuits to prevent electrical interference or improper operation.



Before wiring the resistor(s) to the dynamic braking unit(s), check the min. resistor values shown in the Braking Component Selection tables in Ch.1 of this user manual, and make sure the actual resistance is no less than this value. Damage to the dynamic braking unit and/or resistors and other equipment can result if the wrong resistance value is used.



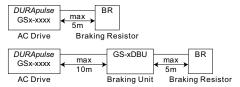
For safety purposes, install an overload relay between the dynamic braking unit and the braking resistor. Wire the overload relay normally closed contact in series with the coil of a magnetic contactor to interrupt the power to the AC drive to prevent damage to the braking resistor in the case of excessive braking or unusually high input voltage.

MAXIMUM WIRING DISTANCES



Wire sizes and wiring distances must comply with applicable electrical codes.

- From DURAPULSE AC Drive (GSx-xxxx) to Braking Resistor (GS-BR-xxxxxxx): 5m [16ft]
- From DURAPULSE AC Drive (GSx-xxxx) to DURAPULSE Dynamic Braking Unit (GS-xDBU): 10m [33ft]
- From DURAPULSE Dynamic Braking Unit (GS-xDBU) to Braking Resistor (GS-BR-xxxxxx): 5m [16ft]



DYNAMIC BRAKING UNIT WIRING TERMINALS



Wire sizes and wiring distances must comply with applicable electrical codes.



Ring terminals are recommended to be used for main circuit wiring. Make sure the terminals are fastened before power is applied.

Ring Terminals

Ring terminals are not required by UL, but they can be used according to the UL conditions of acceptability.

UL Conditions of Acceptability

For use only in Industrial Control Equipment where the acceptability is determined by Underwriters Laboratories Inc.

This component controller has been judged on the basis of the required spacings in the Standard for Power Conversion Equipment, UL 508C, Pollution Degree 2.

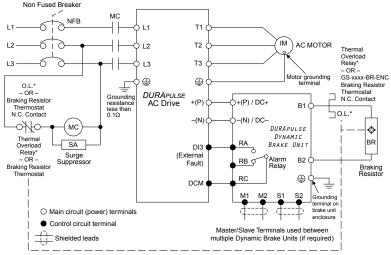
The following shall be considered in the final application:

- 1) Terminals are acceptable for factory or field wiring.
- 2) Device shall be installed in a suitable enclosure.
- Failure mode testing of the voltage sensing circuit, which could result in operation of the DC bus input at transient voltages higher than 800VDC during motor regeneration, was not performed.
- 4) These devices should be mounted and used according to the manufacturer's directions and specifications with regard to compatibility with drive type (see Ratings Section) and braking resistor specification.
- 5) The manufacturer should provide in the end product all literature designating use of the devices as described in Condition of Acceptability 4) above.
- 6) Temperature testing was performed in a 150% outer enclosure and results found acceptable for use in 25°C ambient outside of the 150% outer enclosure. Use at elevated ambients with other enclosure configurations will require heat testing with the actual intended enclosure and the elevated ambient.

BRAKING UNIT WIRING TERMINAL SPECIFICATIONS												
BRAKIN	<i>д U</i> NIT МО	DELS: GS-1D	BU, GS-2DBU, GS-3DBU	, GS-4DBU								
CIRCUIT	TERMIN	AL MARK	WIRE SIZE	SCREW	TORQUE							
Power Input Circuit	+(P), -(N)		10–12 AWG [3.5–5.5 mm ²]	M4	15.6 in·lb [18 kg·cm]							
Braking Resistor	B1	, B2	10–12 AWG [3.5–5.5 mm ²]	M4	15.6 in·lb [18 kg·cm]							
Slave Circuit	Output	M1, M2	18–20 AWG [0.8–0.5 mm ²]	M2	3 in·lb							
	Input	S1, S2	(with shielded wires)		[4 kg·cm]							
Fault Circuit	RA, I	RB, RC	18–20 AWG [0.8–0.5 mm ²]	M2	3 in·lb [4 kg·cm]							
Bi	RAKING UNI	T MODELS: 0	GS-5DBU, GS-6DBU, GS-2	7DBU	[+ KB citi]							
CIRCUIT	TERMIN	AL MARK	WIRE SIZE	SCREW	TORQUE							
Power Input Circuit	DC+	-, DC-	4–6 AWG [21.2–13.3 mm ²]	M8	26 in·lb [30 kg·cm]							
Braking Resistor	B1	, B2	4–6 AWG [21.2–13.3 mm ²]	M8	26 in·lb [30 kg·cm]							
Slave Circuit	Output	M1, M2	18–20 AWG [0.8–0.5 mm ²]	M2	3 in·lb							
Slave Circuit	Input S1, S2		(with shielded wires)		[4 kg·cm]							
Fault Circuit	RA	., RC	18–20 AWG [0.8–0.5 mm ²]	M2	3 in·lb [4 kg·cm]							

DBU Wiring Terminal Specifications

BASIC BRAKING WIRING DIAGRAM



* Although it is recommended, the use of a thermal overload relay in line with the braking resistor is not required. GS-xxxx-BR-ENC braking resistors include a thermostat for thermal protection of the braking resistor, and are the preferred method of protection when available. Orient the braking resistors such that the thermostat is above the resistors in the enclosure, as this will ensure that the thermostat is exposed to the rising air temperature produced by the resistors.



Smaller-capacity DURApulse AC Drives can connect directly to braking resistors, and do not require Dynamic Braking Units for braking. Refer to the "Dynamic Braking Component Selection" section of Chapter 1 to determine which braking components are required for each drive.

Although it is recommended, the use of a thermal overload relay in line with the braking resistor is not required. GS-xxxx-BR-ENC braking resistors include a thermostat for thermal protection of the braking resistor, and are the preferred method of protection when available. Orient the braking resistors such that the thermostat is above the resistors in the enclosure, as this will ensure that the thermostat is exposed to the rising air temperature produced by the resistors.



For overload relay information, Refer to the "Overload Relay" section at the beginning of this chapter.

SPECIFIC BRAKING WIRING DIAGRAMS

Wiring Diagram Index for GS3 Drives

				GS	3 A	C Drive Brak	i Wiri	NG D 1/	AGRAM	ND	EX				
	230	VAC Dr.	IVE	AND MC	то	r Voltage			460	VAC DR	IVE	AND MO	то	r Voltage	
Mo Pov		AC Drive		RAKING UNIT		BRAKING RESISTOR	DIAGRAM		TOR WER	AC DRIVE		RAKING UNIT		BRAKING RESISTOR	DIAGRAM
(нр)	(ĸW)	Part # GS3-	QUANTITY	PART # GS-	QUANTITY			(нр)	(ĸW)	Part # GS3-	QUANTITY	PART # GS-	QUANTITY	PART # GS-	WIRING DIA
1	0.7	21P0			1	21P0-BR	П	1	0.7	41P0			1	41P0-BR	
2	1.5	22P0			1	22P0-BR		2	1.5	42P0]		1	42P0-BR	
3	2.2	23P0			1	23P0-BR		3	2.2	43P0			1	43P0-BR	
5	3.7	25P0	0	n/a	1	25P0-BR	A	5	3.7	45P0	0	n/a	1	45P0-BR	Α
7.5	5.5	27P5			1	27P5-BR		7.5	5.5	47P5			1	47P5-BR	
10	7.5	2010			1	2010-BR-ENC		10	7.5	4010			1	4010-BR	
15	11	2015			1	2015-BR-ENC		15	11	4015			1	4015-BR-ENC	
20	15	2020	1	2DBU	1	2020-BR-ENC		20	15	4020	1	4DBU	1	4020-BR-ENC	
25	18	2025	1	2DBU	1	2025-BR-ENC	D	25	18	4025	1	4DBU	1	4025-BR-ENC	
30	22	2030	1	2DBU	1	2030-BR-ENC		30	22	4030	1	4DBU	1	4030-BR-ENC	Ы
40	30	2040	2	2DBU	2	2040-BR-ENC	F	40	30	4040	1	4DBU	1	4040-BR-ENC	
50	37	2050	2	2DBU	2	2050-BR-ENC	50	40	4050	1	4DBU	1	4050-BR-ENC		
								60	45	4060	1	4DBU	1	4060-BR-ENC	
								75	55	4075	2	4DBU	2	4075-BR-ENC	F
									75	4100	2	4DBU	2	4100-BR-ENC	'

Wiring Diagram Index for GS4 Drives

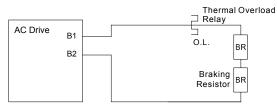
				GS	<u>4</u> A	C DRIVE BR	AKING	g Wiring Diagram Index								
	230	VAC Dri	VE /	AND MOT	OR	VOLTAGE			460	VAC Dri	VE /	AND MO	OR V	OLTAGE		
Мо	TOR		В	RAKING		BRAKING		Motor			B	RAKING	E	BRAKING		
PO	WER	AC		UNIT	RESISTOR			PO	Power			UNIT R		RESISTOR		
(нр)	(ĸW)	DRIVE PART # GS4-	QUANTITY	PART # GS-	QUANTITY	PART # GS-BR-	DIAGRAM #	(нр)	(ĸW)	Drive Part # GS4-	QUANTITY	PART # GS-	QUANTITY	PART # GS-BR-	DIAGRAM #	
1	0.7	21P0			1	080W200		1	0.7	41P0			1	080W750		
2	1.5	22P0			1	200W091		2	1.5	42P0			1	200W360		
3	2.2	23P0			1	300W070		3	2.2	43P0			1	300W250		
5	3.7	25P0			1	400W040	A	5	3.7	45P0			1	400W150	A	
7.5	5.5	27P5	0	n/a	1	1K0W020		7.5	5.5	47P5			1	1K0W075		
10	7.5	2010		11/a	1	1K0W020		10	7.5	4010	0	n/a	1	1K0W075		
15	11	2015			1 1K5W013		15	11	4015	-		1	1K5W043			
20	15	2020			2	1K0W4P3		20	15	4020			2	1K0W016		
25	18	2025			2	1K0W4P3	В	25	18	4025			2	1K0W016	В	
30	22	2030			2	1K5W3P3		30	22	4030			2	1K5W013		
40	30	2040	2	1DBU	4	1K0W5P1		40	30	4040			4	1K0W016	С	
50	37	2050	2	2DBU	4	1K2W3P9	G	50	40	4050	1	4DBU	4	1K2W015	Е	
60	45	2060	2	2DBU	4	1K5W3P3		60	45	4060	1	4DBU	4	1K5W013		
75	55	2075	3	2DBU	6	1K2W3P9	J	75	55	4075	2	3DBU	8	1K0W5P1	н	
100	75	2100	4	2DBU	8	1K2W3P9	К	100	75	4100	2	4DBU	8	1K2W015		
								125	90	4125	2	4DBU	8	1K5W013		
								150	110	4150	1	5DBU	10	1K2W015	L	
								175	132	4175	1	6DBU	12	1K5W012	м	
								200	160	4200	1	6DBU	12	1K5W012		
								250	185	4250	1	7DBU	14	1K5W012	N	
								300	220	4300	2	5DBU	20	1K2W015	0	

		For GS3 230	VAC	C Drives				For GS3 460	VA	C Drives					
AC Drive	B	raking Unit		Braking Resistor	Diag.	AC Drive	Br	aking Unit		Braking Resistor	Diag.				
Part #	#	Part #	#	Part #	Ö	Part #	#	Part #	#	Part #	Ö				
GS3-21P0			1	GS-21PO-BR		GS3-41P0			1	GS-41PO-BR					
GS3-22P0			1	GS-22PO-BR		GS3-42P0			1	GS-42P0-BR					
GS3-23P0			1	GS-23PO-BR		GS3-43P0			1	GS-43P0-BR					
GS3-25P0	0	n/a	1	GS-25PO-BR	A	GS3-45P0	0	n/a	1	GS-45P0-BR	A				
GS3-27P5]		1	GS-27P5-BR		GS3-47P5			1	GS-47P5-BR					
GS3-2010	ļ		1	GS-2010-BR-ENC		GS3-4010			1	GS-4010-BR					
GS3-2015			1	GS-2015-BR-ENC		GS3-4015			1	GS-4015-BR-ENC					
		For GS4 230	VAC	C Drives				For GS4 460	VAG	C Drives					
AC Drive	B	raking Unit		Braking Resistor	ģ	AC Drive	Br	aking Unit		Braking Resistor	ģ				
Part #	#	Part #	#	Part #	Diag.	Part #	#	Part #	#	Part #	Diag.				
GS4-21P0			1	GS-BR-080W200		GS4-41P0			1	GS-BR-080W750					
GS4-22P0	1		1	GS-BR-200W091		GS4-42P0	1		1	GS-BR-200W360	1				
GS4-23P0		n/a	n/a	n/a		n/a	1	GS-BR-300W070		GS4-43P0			1	GS-BR-300W250	
GS4-25P0	0						n/a	n/a	n/a 1		GS-BR-400W040	A	GS4-45P0		n/a
GS4-27P5]		1	GS-BR-1K0W020		GS4-47P5			1	GS-BR-1K0W075]				
GS4-2010]		1	GS-BR-1K0W020		GS4-4010]		1	GS-BR-1K0W075]				
GS4-2015			1	GS-BR-1K5W013		GS4-4015			1	GS-BR-1K5W043					
						Thermal □ Relay	Ov	rerload							
AC Drive	ę		Γ		-[,	٦								
10 5111	-	B1				0.L.									
		B2	_			Г									
							BR								
						L									
								Braking							
1							1 1	Resistor							

Wiring Diagram A: [Drive + 1 Resistor]

Wiring Diagram B: [Drive + 2 Series Resistors]

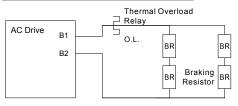
		For GS4 230	VAC	C Drives		For GS4 460VAC Drives						
AC Drive	Br	raking Unit		Braking Resistor	iag.	AC Drive	Br	raking Unit		Braking Resistor	ag.	
Part #	#	Part #	#	Part #	Ξ	Part #	#	Part #	#	Part #	Ξ	
GS4-2020			2	GS-BR-1K0W4P3		GS4-4020			2	GS-BR-1K0W016		
GS4-2025	0	n/a	2	GS-BR-1K0W4P3	в	GS4-4025	0	n/a	2	GS-BR-1K0W016	в	
GS4-2030			2	GS-BR-1K5W3P3		GS4-4030			2	GS-BR-1K5W013		



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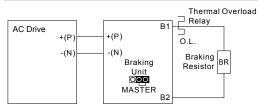
Wiring Diagram C: [Drive + (2 Series + 2 Parallel) Resistors]

Γ	For GS4 460VAC Drives												
l	AC Drive	Br	aking Unit		Braking Resistor	ъ.							
	Part #	#	Part #	#	Part #	Ö							
L	GS4-4040 0 n/a 4 GS-BR-1K0W016 C												



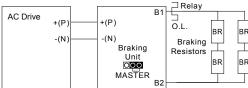
Wiring Diagram D: [Drive + 1 DBU + 1 Resistor]

		For GS3 230	VAC	C Drives				For GS3 460	VAC	C Drives	
AC Drive	Br	aking Unit		Braking Resistor	а в	AC Drive	Br	aking Unit		Braking Resistor	ы в
Part #	#	Part #	#	Part #	ä	Part #	#	Part #	#	Part #	ö
GS3-2020	1	GS-2DBU	1	GS-2020-BR-ENC		GS3-4020	1	GS-4DBU	1	GS-4020-BR-ENC	
GS3-2025	1	GS-2DBU	1	GS-2025-BR-ENC	D	GS3-4025	1	GS-4DBU	1	GS-4025-BR-ENC	
GS3-2030	1	GS-2DBU	1	GS-2030-BR-ENC		GS3-4030	1	GS-4DBU	1	GS-4030-BR-ENC	D
						GS3-4040	1	GS-4DBU	1	GS-4040-BR-ENC	ש
		n/	а			GS3-4050	1	GS-4DBU	1	GS-4050-BR-ENC	
						GS3-4060	1	GS-4DBU	1	GS-4060-BR-ENC	



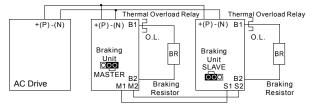
Wiring Diagram E: [Drive + 1 DBU + (2 Series + 2 Parallel) Resistors]

Γ			For GS4 460	VAC	C Drives		
	AC Drive	Br	aking Unit		Braking Resistor	iag.	
	Part #	#	Part #	#	Part #	Di	
	GS4-4050	1	GS-4DBU	4	GS-BR-1K2W015	F	
	GS4-4060	1	GS-4DBU	4	GS-BR-1K5W013	E	
		-			-		ermal Overload Iay
ĺ	AC Drive				B1 - E		



Wiring Diagram F: [Drive + 2 DBUs + 1 Resistor/DBU]

		For GS3 230	VAC	C Drives				For GS3 460	VAC	C Drives	
AC Drive	Br	aking Unit		Braking Resistor	ав.	AC Drive	B	aking Unit		Braking Resistor	ė
Part #	#	Part #	#	Part #	ö	Part #	#	Part #	#	Part #	Dia
GS3-2040	2	GS-2DBU	2	GS-2040-BR-ENC	_	GS3-4075	2	GS-4DBU	2	GS-4075-BR-ENC	-
GS3-2050	2	GS-2DBU	2	GS-2050-BR-ENC	F	GS3-4100	2	GS-4DBU	2	GS-4100-BR-ENC	F

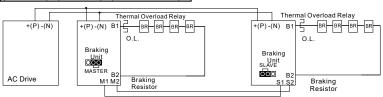


Wiring Diagram G: [Drive + 2 DBUs + 2 Series Resistors/DBU]

		For GS4 230]			
AC Drive	Br	raking Unit		Braking	g Resistor	ŵ	
Part #	#	Part #	#		Part #	Diag	
GS4-2040	2	GS-1DBU	4	GS-BF	R-1KOW5P1		
GS4-2050	2	GS-2DBU	4	GS-BF	R-1K2W3P9	G	
GS4-2060	2	GS-2DBU	4	GS-BF	R-1K5W3P3		
+(P	, ,		(P) - Brał Ur OOT	(N) B1 king hit	O.L. BR BR Braking Resistor		ay Thermal Overload Relay +(P)-(N) B1 O.L. BR Braking Unit SLAVE S1 S2 Braking Resistor

H: [Drive + 2 DBUs + 4 Parallel Resistors/DBU]

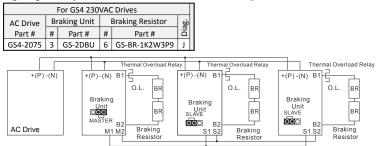
For GS4 460VAC Drives													
AC	Drive	Braking Unit Braking Resistor											
Pa	irt #	#	Part #	#	Part #	Ō							
GS4-4075 2 GS-3DBU 8 GS-BR-1K0W5P1 H													



Wiring Diagram I: [Drive + 2 DBUs + (2 Series + 2 Parallel) Resistors/DBU]

			-			•	
		For GS4 460	VAC	C Driv	es		
AC Drive	Br	aking Unit		Brakiı	ng Resistor		
Part #	#	Part #	#	# Part #			
GS4-4100	2	GS-4DBU	8	GS-I	3R-1K2W015		
GS4-4125	2	GS-4DBU	8	GS-I	3R-1K5W013	1	
	(N)	Br	akir Jnit	I) B1			+(P)-(N) B1 Braking Unit SLAVE SLAVE ST S2 Braking BR BR BR BR BR BR
AC Drive M1					Resistor	L	S1 S2 Braking Resistor
	AC Drive Part # GS4-4100 GS4-4125	AC Drive Br Part # # GS4-4100 2 GS4-4125 2 +(P) -(N)	For GS4 460 AC Drive Braking Unit Part # Part # GS4-4100 2 GS-4DBU GS4-4125 2 GS-4DBU +(P)-(N) +(P) +(P)	For GS4 460VA0 AC Drive Braking Unit Part # # GS4-4100 2 GS-4DBU GS4-4125 2 GS-4DBU +(P)-(N) +(P)-(N) +(P)-(N)	For GS4 460VAC Drive Part # # Parking Unit Braking Part # # Part # # GS4-4100 2 GS-4DBU 8 GS-E GS4-4125 2 GS-4DBU 8 GS-E +(P) -(N) +(P) -(N) Braking Unit Unit GOOD MASTER B2 BASTER B2	AC Drive For GS4 460VAC Drives For GS4 460VAC Drives Braking Unit Braking Resistor Part # Part # Part # GS4-4100 2 GS-4DBU 8 GS-BR-1K2W015 GS4-4125 2 GS-4DBU 8 GS-BR-1K2W013 Thermal Overload R +(P)-(N) +(P)-(N) B1 O.L. BR BR Braking Unit BR BR MASTER B2 M1 M2 Braking Braking	AC Drive Part # Part # Part # Part # GS4-4100 2 GS-4DBU 8 GS-BR-1K2W015 GS4-4125 2 GS-4DBU 8 GS-BR-1K2W013 I Thermal Overload Relay +(P)-(N) B1 OL. BR BR Braking Unit Data BR BR MASTER B2 MASTER B2

Wiring Diagram J: [Drive + 3 DBUs + 2 Series Resistors/DBU]

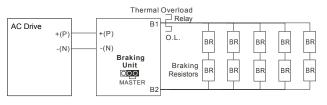


Wiring Diagram K: [Drive + 4 DBUs + 2 Series Resistors/DBU]

	For GS4 230	VAC Drive	es			
AC Drive	e Braking Unit Braking Resistor		Diag.			
Part #	# Part #	#	Part #	Dig		
GS4-2100 4	4 GS-2DBU	8 GS-B	R-1K2W3P9	К		
+(P)-(N) AC Drive	Therm +(P)-(N) B1 Unit WASTER B2 M1 M2	al Overload Relay O.L. BR BR Braking Resistors	H(P) -(N) B1 Braking Unit SLAVE S1 S2 S1 S2	O.L. BR	Thermal Overload +(P)-(N) B1 Braking Unit SLAVE S1 S2 Braking Resistors	Thermal Overload +(P)-(N) B1 Braking Unit S.V/E S.V/E S.S.Z Braking BR BR BR BR BR BR BR BR BR BR

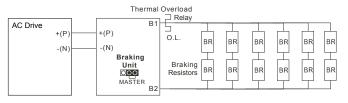
Wiring Diagram L: [Drive + 1 DBU + (2 Series + 5 Parallel) Resistors/DBU]

For GS4 460VAC Drives							
AC Drive	Braking Unit		Braking Resistor				
Part #	#	Part #	#	Part #	Diag.		
GS4-4150	1	GS-5DBU	10	GS-BR-1K2W015	L		



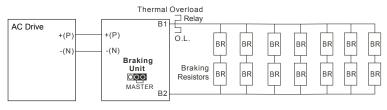
Wiring Diagram M: [Drive + 1 DBU + (2 Series + 6 Parallel) Resistors/DBU]

	For GS4 460VAC Drives								
	AC Drive	Br	aking Unit	В	.g.				
	Part #	#	Part #	#	Part #	Di			
	GS4-4175	1	GS-6DBU	12	GS-BR-1K5W012				
	GS4-4200	1	GS-6DBU	12	GS-BR-1K5W012	М			



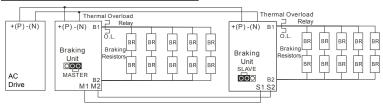
Wiring Diagram N: [Drive + 1 DBU + (2 Series + 7 Parallel) Resistors/DBU]

	For GS4 460VAC Drives							
	AC Drive	Braking Unit		Braking Resistor				
	Part #	#	Part #	#	Part #	ā		
L	GS4-4250	1	GS-7DBU	14	GS-BR-1K5W012	Ν		



Wiring Diagram O: [Drive + 2 DBUs + (2 Series + 5 Parallel) Resistors/DBU]

			-					
Γ	For GS4 460VAC Drives							
	AC Drive	Braking Unit		Braking Resistor				
	Part #	#	Part #	#	Part #	Diag.		
	GS4-4300	2	GS-5DBU	20	GS-BR-1K2W015	0		



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