Non-contacting speed sensor with signal amplifier, inductive-magnetic principle

Speed

- · Cost-effective speed sensor with rectangular-pulse signal output
- Threaded brass sensor tube
- For ferromagnetic toothed wheels from module m2 (m1) up
- Frequency range from approx. 5 Hz to 10,000 Hz
- Push-pull output stage
- · Loadable with 50 mA SINK and 20 mA LOAD
- · High degree of EMC immunity for severe electrical environments
- Wide operating temperature range from -40 °C ... +105 °C
- · Excellent vibration and shock resistance
- Face side is metal-enclosed
- Rugged construction, housing IP66 / IP67
- · Choice of lengths, screw-in threads and electrical terminations



Non-contacting Speed Sensor of Series FAJ11...

Method of operation of the speed sensor

Non-contacting speed sensors of the FAJ11... series are basically designed for speed sensing. The rotation of ferromagnetic toothed wheels is sensed by means of a sensing coil and converted by a signal amplifier into a rectangular signal. The frequency of the rectangular signal is proportional to the speed. Apart from speed, the sensors are adapted to sense any movement of ferromagnetic parts. The rectangular signal lends itself to evaluation or transformation by a variety of devices.

Details of the speed sensor

· Inputs may be generated by ferromagnetic toothed wheels, bolt heads, lands detects holes, openings or grooves in ferromagnetic parts

- · Wear- and maintenance-free due to contactless sensing
- Wide temperature range through use of high-grade automotive-class components
- · Resistant to oil spray and lubricants, even at elevated temperatures
- · Requirements of the classification societies many times far excelled
- · Extensive electric snubber circuits integrated for protection
- · Simple screw-in mounting by threaded sensor tube
- Up to 10 signal-processing NORIS devices can be connected
- · Suitable measuring transducers and limit-value switches are available

Output of the speed sensor

The output signal is a noise-immune, rectangular signal whose frequency is proportional to the speed. The voltage range is within the load voltage and load-dependent. The geometry of the passing object determines the pulse duty factor. In the case of a toothed wheel, it corresponds to approx. 50%. The output circuit is a push-pull stage. Short circuit protection is provided by a 60 Ω PTCresistor. Spurious pulses are intercepted by an internal varistor against minus. The push-pull output stage can be used as a NPN output (current sinking) as well as a PNP output (current sourcing). The output voltage is galvanically coupled to the load voltage

Inductive-magnetic principle of the speed sensor

The measuring element is a sensing coil and an iron core with a permanent magnet mounted. Ferromagnetic objects with an interrupted surface as they pass the sensor cause the constant field of the magnet to be changed and induce a voltage in the sensing coil. The frequency of this voltage is proportional to the speed of movement (rotational speed). In the case of the induction principle, the level of the induced voltage is dependent on the rate at which the magnetic flux is changed (dynamic principle). This means that the detection of very slow movements or even of "standstill" is not possible. The lower limit frequency is the lower the more abrupt change in the geometry of the object passing the sensor and the shorter the distance between the object and the sensor. The recommended distance to the toothed wheel for module > m2 is 1.5 mm. At high frequencies, the inductivity of the sensing coil causes the induced voltage to be heavily dampened (reduced) so that evaluation is no longer possible. This results in a range of application from approx. 5 Hz to 10,000 Hz or, under optimum installation conditions (true running, low-vibration environment), up to 15,000 Hz. The capture of small

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Distance

toothed wheels up to module m1 is possible by distance decelerating (recommended 0.8 mm). Reversed for wide modules > m5 the recommended distance could be a couple of millimeters. The inductive-magnetic principle is direction-insensitive.

Installation and connecting information and trouble shooting, see separate leaflet

Technical Data

| | Series FAJ11 | | | |
|-----------|----------------------------|---|--|--|
| General | Supply voltage | U 24 V/DC, range 8 32 V/DC ±10% harmonic content | | |
| | Current consumption | Approx. 4 mA @ 24V/DC + switching current (max. 20 mA) | | |
| | Reverse voltage protection | Integrated | | |
| | Over voltage protection | Integrated | | |
| Input | Measuring principle | Inductive-magnetic | | |
| | Frequency range | Approx. 5 Hz 10,000 Hz (dependent from module and distance) under optimum installation conditions up to 15,000 Hz | | |
| | Scan object | Ferromagnetic toothed wheel: >m2, tooth face width >5 mm (spur gear DIN867); Hole: Ø >5 mm, web >2 mm, depth >4 mm; Groove: >4 mm, web >2 mm, depth >4 mm | | |
| | Distance | 0.2 3 mm and more, recommended 1.5 mm ±0.5 | | |
| | Output circuit | Push-pull output stage | | |
| Output | Output signal | NORIS standard signal, square wave, level approx. U _{sup} , galvanically coupled with supply voltage | | |
| | Output level | High: approx. U _{sup} +1.5 V @ 1 mA, U _{sup} +1.8 V @ 5 mA, U _{sup} +2.2 V @ 10 mA Low: approx. U _{sup} +0.5 V @ 1 mA, U _{sup} +0.8 V @ 5 mA, U _{sup} +1.2 V @ 10 mA | | |
| | Output resistance | Series resistance R _i : 60 Ω | | |
| | Switching current | NPN (SINK) 50 mA, PNP (LOAD) 20 mA, permanent short-circuit proof | | |
| | Rise time | ≥ 10 V/µs | | |
| nfluences | Operating temperature | -40 +105°C | | |
| | Climatic test | DIN IEC 60068-T2-1/-2/-30 | | |
| | Vibration resistance | DIN IEC 60068-T2-6: 10 g @ 5 2,000 Hz (Sinus) DIN EN 61373: 30 g _{eff} @ 20 500 Hz (Random) | | |
| | Shock resistance | DIN IEC60068-T2-27: 1,000 m/s² @ 6 ms | | |
| | Degree of protection | EN 60529: housing IP66 / IP67; connection A IP65, connection C/E/H/X IP67 | | |
| tali | ESD | IEC 61000-4-2: ± 6 kV/CD; ±8 kV/AD | | |
| nen | HF-interference immunity | IEC 61000-4-3: 10 V/m f=80 MHz 2,000 MHz, 80% AM @ 1 kHz | | |
| ronr | Burst | IEC 61000-4-4: ±2 kV/PL; ±1 kV/DL | | |
| Envir | Surge | IEC 61000-4-5: ±0.5 kV/DM (Rg=2 Ω); ±1 kV/DM (Rg=42 Ω); ±1 kV/CM (Rg=12 Ω) | | |
| | Conducted HF-interference | IEC 61000-4-6: 10 V _{eff} f=150 kHz 80 MHz, 80% AM @ 1 kHz | | |
| | Conducted LF-interference | IEC 60553: 3 V _{eff} 0.05 10 kHz | | |
| | Interference emission | CISPR 16-1, 16-2: EMC2 | | |
| | Insulation voltage | 500 V/AC, 50 Hz @ 1 min | | |
| Other | Storage temperature | Recommended -25 +70 °C (possible -40 +105 °C) | | |
| | Mounting | Screw-in by threaded sensor tube | | |
| | Pressure resistance | Measuring tip up to 5 bar | | |
| | Electrical connection | See drawing | | |
| | Recommended cable length | 1,000 m / 1 kHz @ 0.5 mm² screened | | |
| | Installation position | Any | | |
| | Installation mode | Direction-insensitive | | |
| | Material | Adapter: aluminium chromalized, sensor tube: brass | | |
| | Weight | Approx. 100 300 g (dependent to connection and length) | | |
| | Approvals | CE; ABS, DNV, GL, LR | | |

Type Key / Standard Variants

| FAJ11 - 02 15 - X03 (-) (FAJ11-0215-X03) 1 2 3 * 5 * *Pos. 4, 6 not applicable for series FAJ11 | | | | |
|---|--|-----------------------------------|--------------------------|--|
| 1 | Device and series (basic versions, other or | er on customer request available) | | |
| FAJ11 Non-contacting speed sensor, inductive-magnetic principle, series cylindric with threaded brass sensor tube, plug socket and sensor socket aluminium ch lized, electronic integrated in sensor tube | | | | |
| 2 | Nominal length (drawing L1, L2) | 3 | Thread type (drawing G1) | |
| 02 | L1=60 mm, L2=5 mm | 15 | M18x1 | |
| 03 | L1=80 mm, L2=5 mm | 23 | M18x1,5 | |
| 04 | L1=100 mm, L2=20 mm | 88 | 5/8" - 18 UNF | |
| 05 | L1=120 mm, L2=40 mm | | | |
| 5 | Electrical connection | | | |
| Α | DIN43650-A pin connector, 3 terminals + PE (solenoid valve 30 x 30) | | | |
| С | Mil 14-5PN VG95234 pin connector, 5 terminals | | | |
| Е | EURO M12x1, pin connector, 5 terminals, contact gold-plated | | | |
| H1 | DIN72585 Bajonette pin connector, 4 terminals, coding 1 (BK) | | | |
| X | Cable jumper with jacketlength (drawing K1) (standard: X03=0.5m; X05=2.0m; X06=3.0m; X07=5.0m; X08=7.5m; X09=10.0m) | | | |

Dimensions, Connection, Diagram

Sensor tube



Terminal DIN43650 A: type FAJ11-xxxx-A Supplied with female connecto





Terminal Mil 14-5PN: type FAJ11-xxxx-C

Supplied without female connector (accessory set ZL4-1A)



Terminal Euro M12x1: type FAJ11-xxxx-E Supplied without female connector (accessory set ZL4-2A)



Terminal DIN72585 Bajonette: type FAJ11-xxxx-H Supplied without female connector (accessory set ZL4-5)

code 1 coding nibs 1: + 2: -4 - 1 C 3: Q 0 4: GROUND



L1

3 Optional with degree of protection IP69K

Terminal cable jumper: type FAJ11-xxxx-X

brown: + green: white: Q Shielding: GROUND

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Elementary circuit diagramm (push-pull output stage)

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NPN- or PNP inputs may be connected.





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